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## Problem 1

1. By Neyman-Pearson factorization criterion,  $T$  is sufficient iff there exists a function  $g_P(\cdot)$  such that

$$\frac{\prod_{i=1}^n f_P(x_i)}{\prod_{i=1}^n f_{P_0}(x_i)} = g_P(T(x^{(n)}))$$

Taking log on both sides yields:

$$\varphi(x_1) + \cdots + \varphi(x_n) = \log g_P(T(x^{(n)})) \triangleq \psi(T(x^{(n)}))$$

i.e.  $\varphi_P \in \mathcal{S}$ . In other words,  $T$  is sufficient if and only if  $\varphi_P \in \mathcal{S}$ .

2. Since by definition  $\mathbb{P}$  is exponential of order  $s$  if and only if  $s$  is the smallest positive integer such that

$$f_P(x) = \exp \left\{ \sum_{i=1}^s \eta_i(P) \tau_i(x) - B(P) \right\} h(x)$$

then it is easy to prove that  $\dim\{\text{span}\{\tau_1, \dots, \tau_s\}\} = s$ , where  $\text{span}\{\tau_1, \dots, \tau_s\}$  is the linear space spanned by  $\tau_1, \dots, \tau_s$ . This is because if  $\dim\{\text{span}\{\tau_1, \dots, \tau_s\}\} < s$ , then there exists an integer  $s' < s$ , such that  $f_P(x)$  admits the above form.

On the other hand, notice

$$\varphi_P(x) = B(P_0) - B(P) + \sum_{i=1}^s (\eta_i(P) - \eta_i(P_0)) \tau_i(x)$$

Thus we have  $V = \text{span}\{\mathbb{I}, \tau_1, \dots, \tau_s\}$ , where  $\mathbb{I}$  is the constant function. [*ed. note:* The above shows  $V \subseteq \text{span}\{\mathbb{I}, \tau_1, \dots, \tau_s\}$ , and  $V$  cannot be of lower dimension, or else we could work backwards and write the densities  $f_P(x)$  using fewer  $\tau_i$ .] To sum up,  $\dim(V) = s + 1$  if and only if  $P$  is of order  $s$ .

3. Let  $t_1 = T(x_0, y_1), t_2 = T(x_0, y_2)$ . Without loss of generality, we shall assume  $y_1 < y_2$  and

$$t_1 < T(x_0, y) < t_2, \quad y \in (y_1, y_2) \tag{1}$$

Otherwise, we can always define  $y'_1 = \sup\{y | y \leq y_2, T(x_0, y) = t_1\}$ ,  $y'_2 = \inf\{y | y \geq y_1, T(x_0, y) = t_2\}$ . Then by redefining  $y_1 = y'_1, y_2 = y'_2$ , we have  $T(x_0, y_1) = t_1, T(x_0, y_2) = t_2$ , and  $\varphi(y_1) = \varphi(y_2)$ .

Since  $\varphi(y_1) = \varphi(y_2)$  and  $\varphi$  is continuous, then there exists a  $y_0 \in (y_1, y_2)$  such that  $y_0$  is a local maximal or local minimum. Without loss of generality, suppose

$$\varphi(y_0) \geq \varphi(y), \quad y \in [y_1, y_2] \quad (2)$$

The other case can be proved analogously.

From (1), we know that

$$t_1 < t_0 = T(x_0, y_0) < t_2$$

Moreover,

$$\psi(t_0) = \varphi(y_0) + \varphi(x_0) \geq \varphi(y) + \varphi(x_0)$$

for all  $y \in (y_1, y_2)$ , where the last inequality follows from (2)

Therefore it follows from (1) that

$$\psi(t_0) \geq \psi(t), \quad t \in (t_1, t_2) \quad (3)$$

Thus there exists an interval  $U(x_0, \epsilon)$ , which is of radius  $\epsilon$  and around  $x_0$ , such that for all  $x \in U(x_0, \epsilon)$ , we have

$$T(x, y_1) < t_0 < T(x, y_2) \quad (4)$$

and

$$t_1 < T(x, y_0) < t_2 \quad (5)$$

By continuity of  $T$  and (4), we know that  $\forall x$ , there exists a  $y_x \in (y_1, y_2)$ , such that  $T(x, y_x) = t_0$

Hence when  $x \in U(x_0, \epsilon)$ , we have

$$\psi(t_0) = \psi(T(x, y_x)) = \varphi(x) + \varphi(y_x) \quad (6)$$

$$\leq \varphi(x) + \varphi(y_0) = \psi(T(x, y_0)) \quad (7)$$

$$\leq \psi(t_0) = \varphi(x_0) + \varphi(y_0) \quad (8)$$

where the inequality in (7) follows from (2) and the inequality in (8) follows from (3) and (5). Moreover, none of the inequality above can hold strictly. Thus

$$\varphi(x) = \varphi(x_0), \quad x \in U(x_0, \epsilon)$$

4. Take any  $\varphi_1$  and  $\varphi_2 \in \mathcal{S}$ , we show that there exists a constant  $a$  such that  $\varphi = \varphi_1 - a\varphi_2$  and  $\varphi$  satisfies the conditions in previous part. Therefore by the result from that part we know that  $\varphi(x) = \varphi(x_0)$  when  $x$  is in some small neighborhood of  $x_0$  for any fixed  $x_0$ . Since  $x_0$  is arbitrary, by continuity of  $\psi$ , we can conclude there must exist a constant  $b$  such that  $\varphi = b$ . i.e.  $\varphi_2 = a\varphi_1 + b$ . This implies  $\dim(V) \leq \dim(S) \leq 2$ , which further implies  $\mathbb{P}$  is of order 1.

We now prove the existence of  $\varphi$ :

*proof:* Without loss of generality, suppose  $\varphi_1$  is not a constant function. Then there must exist  $y_1 \neq y_2$  such that  $\varphi_1(y_1) \neq \varphi_1(y_2)$ .

Therefore

$$T(x_0, y_1) \neq T(x_0, y_2) \quad \forall x_0 \in \mathcal{X}$$

Moreover, if we let  $a = \frac{\varphi_2(y_1) - \varphi_2(y_2)}{\varphi_1(y_1) - \varphi_1(y_2)}$ , then it follows that

$$\varphi_2(y_1) - a\varphi_1(y_1) = \varphi_2(y_2) - a\varphi_1(y_2)$$

Now let  $\varphi = \varphi_2 - a\varphi_1$ . By the discussion at the beginning of the proof, we have  $\varphi = b$  for some constant  $b$ . Since  $\varphi_1, \varphi_2$  are arbitrarily chosen, one can conclude that  $\dim(S) \leq 2$

## Problem 2

1. The log likelihood function is given by

$$l(\theta) = \sum_i -\frac{1}{2} \frac{(y_i - \theta)^2}{\sigma_{a_i}^2}$$

Taking derivative and set it to zero, we have

$$\sum_i \frac{y_i}{\sigma_{a_i}^2} = \hat{\theta} \sum_i \frac{1}{\sigma_{a_i}^2}$$

Therefore

$$\hat{\theta} = \frac{\sum_i y_i / \sigma_{a_i}^2}{\sum_i 1 / \sigma_{a_i}^2}$$

2. Since  $l''(\theta) = -1/\sigma_a^2$ , hence

$$I(\theta) = n\mathbb{E}_{(y,a)}(1/\sigma_a^2) = n \left( \frac{p}{\sigma_1^2} + \frac{1-p}{\sigma_2^2} \right)$$

3. By asymptotic theory of MLE we know that  $\hat{\theta}$  is asymptotically distributed as  $\mathcal{N}(\theta, 1/I(\theta))$ . Since in our setting  $I(\theta)$  does not depend on  $\theta$  and hence can be used for inference. However, in this case it is obvious that the conditional variance of  $\hat{\theta}$  given  $(a_1, \dots, a_n)$ , which is given by the inverse of the observed fisher information, a.k.a  $1/\hat{I}(\theta) = (\frac{n_1}{\sigma_1^2} + \frac{n_2}{\sigma_2^2})^{-1}$ , is a more meaningful quantity.

If we use the unconditional variance to form a confidence interval, it would not have the right coverage. For example, let  $\sigma_1^2 = 100$ ,  $\sigma_2^2 = 1$ ,  $n_1 = 9$ ,  $n_2 = 1$ ,  $p = 0.6$  then if we use the unconditional variance, the approximate 95% confidence interval is given by

$$\hat{\theta} \pm 1.96/\sqrt{I(\theta)} = \hat{\theta} \pm 1.96/\sqrt{5.05}$$

where as the correct 95% confidence interval (based on conditional variance) is

$$\hat{\theta} \pm 1.96/\sqrt{\hat{I}(\theta)} = \hat{\theta} \pm 1.96/\sqrt{1.09}$$

Admittedly this example is quite extreme in that the experimenter was really unlucky in picking the bad equipment 9 times out of 10. But the main point is that as statisticians, we should always use the relevant variance estimate.